

Sec. 7.4. Matrix Representation of Linear Operators.

Defn $T: V \rightarrow V$ linear is called l. operator on V .

- Let $\mathcal{B} = \{v_1, v_2, \dots, v_n\}$ be a basis for V . Then for each $v \in V$, there are unique scalars $c_1, \dots, c_n$ such that

$$v = c_1 v_1 + c_2 v_2 + \dots + c_n v_n.$$

- Isomorphism $\phi_{\mathcal{B}}: V \rightarrow \mathbb{R}^n$ $\phi_{\mathcal{B}}(v) = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$.

- Defn Coordinate vector of v relative to $\mathcal{B}$.

$$[v]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} \quad (\mathcal{B}\text{-coordinate of } v)$$

$$\mathbb{R}^2 \quad \mathcal{B} = \{\underline{e}_1, \underline{e}_2\}, \quad \begin{bmatrix} 2 \\ 3 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

- Inverse $\phi_{\mathcal{B}}^{-1}: \mathbb{R}^n \rightarrow V$ $\phi_{\mathcal{B}}^{-1}([v]_{\mathcal{B}}) = v$.

$$T: V \rightarrow V.$$

$$\phi_{\mathcal{B}}: V \rightarrow \mathbb{R}^n$$

• Composite $\phi_B \circ T \circ \phi_B^{-1} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a l. operator on $\mathbb{R}^n$.

$$\mathbb{R}^n \xrightarrow{\phi_B^{-1}} V \xrightarrow{T} V \xrightarrow{\phi_B} \mathbb{R}^n.$$

$$\phi_B \circ T \circ \phi_B^{-1} ()$$

• Let A ($n \times n$) be the standard matrix of $\phi_B \circ T \circ \phi_B^{-1}$.

• Defn. A is called the matrix repr. of T with respect to $\mathcal{B}$, denoted by $[T]_{\mathcal{B}}$.

($\mathcal{B}$ -matrix). $\mathcal{B} = \{v_1, v_2, \dots, v_n\}$.

• Claim $[T]_{\mathcal{B}} = \begin{bmatrix} [T(v_1)]_{\mathcal{B}} & [T(v_2)]_{\mathcal{B}} & \dots & [T(v_n)]_{\mathcal{B}} \end{bmatrix}$.

Pf: Note $v_j = 0v_1 + 0v_2 + \dots + 1v_j + 0 \dots + 0v_n$.

$$\phi_B(v_j) = [v_j]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \leftarrow j\text{th entry} = e_j.$$

$$\phi_B^{-1}(e_j) = v_j$$

Let A be the standard matrix of $\phi_B^T \phi_B^{-1}$.

Look at the j th col of A

$$A e_j = \phi_B^T \phi_B^{-1}(e_j) = \phi_B^T(v_j) = [\tau(v_j)]_B.$$

##

Ex 1 $T: \mathcal{P}_2 \rightarrow \mathcal{P}_2$ $T(p(x)) = p(0) + 3p'(1)x + p(2)x^2$.

$\mathcal{B} = \{v_1, v_2, v_3\}$ is a basis for $\mathcal{P}_2$. Find $[T]_{\mathcal{B}}$.

$$T(v_1) = 1 + 3 \cdot \overset{p'(1)}{0} x + 1 x^2 \quad [T(v_1)]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$T(v_2) = 0 + 3 \cdot \overset{(x)'|_{x=1}}{1} x + 2 x^2 \quad [T(v_2)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 3 \\ 2 \end{bmatrix}$$

$$T(v_3) = 0 + 3 \cdot 2 x + 4 x^2 \quad [T(v_3)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 6 \\ 4 \end{bmatrix}$$

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 6 \\ 1 & 2 & 4 \end{bmatrix}.$$

Ex 2. $U: M_{2 \times 2} \rightarrow M_{2 \times 2}$ $U(A) = A^T$. Find $[U]_{\mathcal{B}}$.

$$\mathcal{B} = \left\{ \underset{v_1}{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}, \underset{v_2}{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}, \underset{v_3}{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}, \underset{v_4}{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}} \right\}.$$

$$U(v_1) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = v_1 + 0v_2 + 0v_3 + 0v_4, \quad [U(v_1)]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$U(v_2) = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} = v_3$$

$$[U(v_2)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$[U]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$U(v_3) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = v_2$$

$$[U(v_3)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$U(v_4) = v_4$$

$$[U(v_4)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Defn $T: V \rightarrow V$ linear.

a nonzero vector $v \in V$ is said to be an eigenvector of T if $T(v) = \lambda v$ for some scalar λ . eigenvalue λ .

$$\text{Ex 3: } \mathcal{D}: C^\infty \rightarrow C^\infty \quad \mathcal{D}(f) = f'$$

$$\mathcal{D}(e^{at}) = a e^{at} \text{ for any real number } a.$$

- any real number is an eigenvalue of $\mathcal{D}$ and any exponential fcn is an eigenvector of $\mathcal{D}$.

$\mathcal{D}$ has infinitely many eigenvalues and infinitely many l. indep eigenvectors.

$$\text{Ex 4 } U: M_{2 \times 2} \rightarrow M_{2 \times 2} \quad U(A) = A^T.$$

For Any nonzero symmetric matrix A , $U(A) = A^T = A$

A is an eigenvector of U with $\lambda = 1$.

For any nonzero skew-symm matrix A , $U(A) = A^T = -A$

$$(A^T = -A)$$

A is an eigenvector of U with $\lambda = -1$.

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

(p 42, U has only two eigenvalues $\lambda = +1$, and $\lambda = -1$.)

Claim Let $T: V \rightarrow V$ linear. and $\mathcal{B}$ be a finite basis for V .

Let A be the standard matrix of $\phi_{\mathcal{B}} T \phi_{\mathcal{B}}^{-1}$, i.e. $A = [T]_{\mathcal{B}}$.

Then the following are true.

► (a) v is an eigenvector of T iff $[v]_{\mathcal{B}}$ is an eigenvector of A .

(b) v is in the null space (or range of T) iff

$[v]_{\mathcal{B}}$ is in the null space (or col space) of A .

► (c) T is invertible iff A is invertible. Moreover

$$[T^{-1}]_{\mathcal{B}} = A^{-1}.$$

► Ex 1 conti find a basis for null space of T and range of T .

$$\mathcal{B} = \{1, x, x^2\}.$$

► $A = [T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 6 \\ 1 & 2 & 4 \end{bmatrix}.$

$\left\{ \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} \right\}$ form a basis for Null A .

$$\phi_B^{-1}\left(\begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix}\right) = 0 \cdot 1 + (-1)X + 2X^2 = -X + 2X^2$$

$\{-X + 2X^2\}$ form a basis for the null space of T .

$\left\{\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 2 \end{bmatrix}\right\}$ form a basis for $\text{Col } A$.

$\{1 + X^2, 3X + 2X^2\}$ form a basis for the range of T .

Ex. 2 ^{conti} Find a basis for each eigenspace of U .

$$\mathcal{B} = \left\{ \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}_{V_1}, \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_{V_2}, \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}_{V_3}, \underbrace{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}}_{V_4} \right\}. \quad [U]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = A$$

$$\text{CP of } A = (t+1)(t-1)^3. \quad \lambda_1 = -1, \quad m_1 = 1$$

$$\lambda_2 = 1, \quad m_2 = 3.$$

Ex 1 ... $\left\{\begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \end{bmatrix}\right\}$ form a basis for E_{λ_1} .

$$\phi_B^{-1}\left(\begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \end{bmatrix}\right) = 0 \cdot V_1 + 1 \cdot V_2 + (-1) \cdot V_3 + 0 \cdot V_4 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}.$$

U has 2 eigenvalues $\lambda_1 = -1$, $\lambda_2 = 1$.

$\left\{ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}$ form a basis for E_{λ_1} of U .

$\underline{E_{\lambda_2} \text{ of } A}$... $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ form a basis for E_{λ_2} of A .

$\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ form a basis for E_{λ_2} of U .

Exercise Sec. 7.4. T&F, 11, 12, 16, 26, 45.

51 ~ 53. $T: V \rightarrow W$ linear.
 $\mathcal{B}$ $\mathcal{C}$.

$[T]_{\mathcal{B}}$

期末考 6/27 (三) 9:20 ~ 11:00am

Ch 5, Ch 6, Sec. 7.1, 7.2, 7.3, 7.4.

July 2 (-)

• 12:20 ~ 13:00 Check exam paper at BL 113.

• 11am announce final scores on web.

• 2pm announce ^{final} grade.

• No change after 5 pm.

Sec. 7.5 Inner Product Space.

Defn. An inner product on a VS V is a real-valued function, that assigns any pair of vectors u and v a scalar, denoted by $\langle u, v \rangle$, such that for any $u, v, w \in V$ and scalar c , the following are satisfied.

(1) $\langle u, u \rangle > 0$ for any $u \neq 0$

(2) $\langle u, v \rangle = \langle v, u \rangle$.

(3) $\langle u+w, v \rangle = \langle u, v \rangle + \langle w, v \rangle$.

(4) $\langle cu, v \rangle = c \langle u, v \rangle$.

• a vector space with an inner product is called an inner product space.

Defn Norm $\|v\| = \sqrt{\langle v, v \rangle}$.

unit vector $\|v\| = 1$.

distance btw u and $v = \|u - v\|$.

Ex. 1 $V = \mathbb{R}^n$. $\underline{u} \cdot \underline{v}$ is also an inner product.

Ex. 2. $V = C([a, b])$. $\underline{u} \cdot \underline{v} = u_1 v_1^* + u_2 v_2^* + \dots + u_n v_n^*$.

$$\langle f, g \rangle = \int_a^b f(t) g(t) dt.$$

$$(2) \langle g, f \rangle = \int_a^b g(t) f(t) dt = \int_a^b f(t) g(t) dt = \langle f, g \rangle.$$

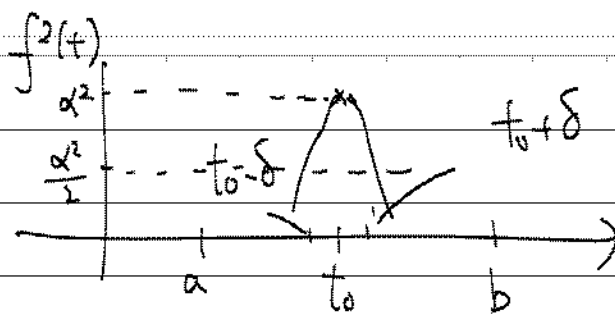
$$(3) \langle f_1 + f_2, g \rangle = \int_a^b (f_1 + f_2) g dt = \int_a^b f_1 g dt + \int_a^b f_2 g dt \\ = \langle f_1, g \rangle + \langle f_2, g \rangle.$$

$$(4) \langle cf, g \rangle = c \langle f, g \rangle.$$

(1) If $f(t) \neq 0(t)$ in $t \in [a, b]$, then $f(t) \neq 0$ for some $t = t_0 \in [a, b]$.

$f^2(t)$ is also continuous in $[a, b]$. $f(t_0) = \alpha \neq 0$.

$$f^2(t_0) = \alpha^2 > 0.$$



$$f^2(t) > \frac{\alpha^2}{2} \quad \text{for } t \in [t_0 - \delta, t_0 + \delta].$$

$\exists \delta > 0$ such that whenever $|t - t_0| < \delta$, $f^2(t) > \alpha^2/2$.

$$\langle f, f \rangle = \int_a^b f^2(t) dt \geq \int_{t_0 - \delta}^{t_0 + \delta} f^2(t) dt.$$

$$> \int_{t_0 - \delta}^{t_0 + \delta} \frac{\alpha^2}{2} dt = 2\delta \cdot \frac{\alpha^2}{2} = \delta \alpha^2 > 0.$$

$\int_a^b f(t)g(t)dt$ is an inner product.

Ex. 3. $V = M_{m \times n}$. $\langle A, B \rangle = \text{trace}(AB^T)$

Frobenius inner product.

In P74, $\text{trace } AB^T = a_{11}b_{11} + a_{12}b_{12} + \dots + a_{1n}b_{1n} + a_{21}b_{21} + \dots + a_{mn}b_{mn}$

$$(1) \langle A, A \rangle = a_{11}^2 + \dots + a_{nn}^2 = \dots + a_{nn}^2 > 0 \quad \text{if some } a_{ij} \neq 0.$$

$A \neq 0$

$$(2). \langle A, B \rangle = \langle B, A \rangle.$$

$$(3) \langle A_1 + A_2, B \rangle = \langle A_1, B \rangle + \langle A_2, B \rangle.$$

$$(4) \langle cA_1, B \rangle = c \langle A_1, B \rangle.$$

$$\langle A, B \rangle = \text{trace}(AB^T) \text{ is an inner product.}$$

$$\text{In fact } \text{trace}(AB^T) = \text{trace}(BA^T) = \text{trace}(A^TB) = \text{trace}(B^TA)$$

Defn u and v are orthogonal if $\langle u, v \rangle = 0$.

orthogonal set, orthogonal basis, orthonormal basis.

Let $\{v_1, v_2, \dots, v_n\}$ be an orthonormal basis for V .

For any $v \in V$, we have

$$v = \langle v, v_1 \rangle v_1 + \langle v, v_2 \rangle v_2 + \dots + \langle v, v_n \rangle v_n$$

Gram-Schmidt Process.

$$S = \{u_1, \dots, u_k\} \text{ basis for } V \xrightarrow{\text{G.S.}} S = \{v_1, v_2, \dots, v_k\} \\ \text{orthogonal basis for } V.$$

$$v_1 = u_1$$

$$v_2 = u_2 - \frac{\langle u_2, v_1 \rangle}{\|v_1\|^2} v_1$$

$$v_3 = u_3 - \frac{\langle u_3, v_1 \rangle}{\|v_1\|^2} v_1 - \frac{\langle u_3, v_2 \rangle}{\|v_2\|^2} v_2.$$

$$\text{Ex. } M_{2 \times 2} \quad \mathcal{B} = \left\{ \underset{v_1}{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}, \underset{v_2}{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}, \underset{v_3}{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}, \underset{v_4}{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}} \right\}$$

$$\langle v_i, v_j \rangle = 0, \quad \|v_i\| = 1, \quad \mathcal{B} \text{ is an orthonormal basis for } M_{2 \times 2}.$$

$$\text{Ex. } \mathcal{P}_2, \quad \mathcal{B} = \left\{ \overset{u_1}{1}, \overset{u_2}{x}, \overset{u_3}{x^2} \right\}$$

$$\langle p_1(x), p_2(x) \rangle = \int_{-1}^1 p_1(x) p_2(x) dx.$$

$$\langle u_1, u_3 \rangle = \int_{-1}^1 1 \cdot x^2 dx = \frac{2}{3} \neq 0.$$

Use GS process

$$V_1 = u_1 = 1, \quad \|v_1\|^2 = \langle v_1, v_1 \rangle = \int_{-1}^1 1 \cdot 1 dx = 2.$$

$$V_2 = u_2 - \frac{\langle u_2, v_1 \rangle}{\|v_1\|^2} v_1 = x - \frac{\langle x, 1 \rangle}{2} 1 = x.$$

$$\langle x, 1 \rangle = \int_{-1}^1 1 \cdot x dx = 0$$

$$\|v_2\|^2 = \int_{-1}^1 x \cdot x dx = \frac{2}{3}.$$

$$V_3 = u_3 - \frac{\langle u_3, v_1 \rangle}{\|v_1\|^2} v_1 - \frac{\langle u_3, v_2 \rangle}{\|v_2\|^2} v_2$$

$$= x^2 - \frac{\langle x^2, 1 \rangle}{2} 1 - \frac{\langle x^2, x \rangle}{\frac{2}{3}} x = x^2 - \frac{1}{3}.$$

$$\langle x^2, 1 \rangle = \frac{2}{3}, \quad \langle x^2, x \rangle = \int_{-1}^1 x^2 \cdot x dx = 0$$

$$\|v_3\|^2 = \int_{-1}^1 (x^2 - \frac{1}{3})^2 dx = \frac{8}{45}.$$

$\left\{ \frac{1}{\sqrt{2}}, \frac{x}{\sqrt{\frac{2}{3}}}, \frac{x^2 - \frac{1}{3}}{\sqrt{\frac{8}{45}}} \right\}$ form an orthonormal basis for $\mathcal{P}_2$.

Normalized Legendre Polynomial.

Orthogonal complement $S^\perp, W^\perp$.

Let W be a subspace of V . Then for any $v \in V$, there is a unique $w \in W$ and $z \in W^\perp$ such that $v = w + z$.

Let $\{w_1, \dots, w_k\}$ be an orthonormal basis for W , then $w = \langle v, w_1 \rangle w_1 + \langle v, w_2 \rangle w_2 + \dots + \langle v, w_k \rangle w_k$.

w is the OP of v onto W .

w is the vector in W that is closest to v .